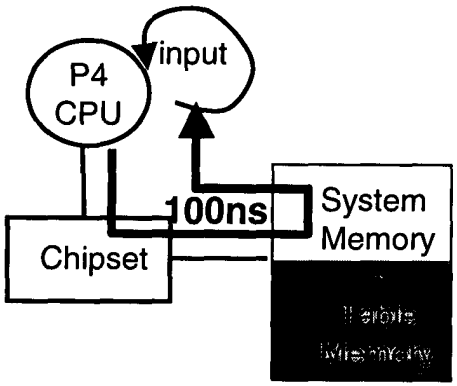
Figure 1(a)

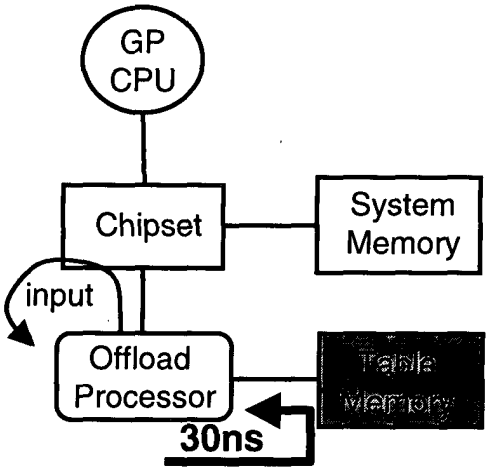
Properties of DFA and NFA techniques used on conventional microprocessors	**Storage: Bound on # of States (for an R character Regular Expression)**	**Evaluation tim (for N bytes of input) [order of]**
Deterministic Finite State Automata or DFA running on a GP CPU	**2^R** (needs very large memory)	**N** memory access cycles
Non-Deterministic Finite State Automata or NFA running on a GP CPU	**R**	**R * N** cpu cache+branch cycles

Figure 1(b)

CPU walking DFA table in DRAM



Coprocessor closer to table in SRAM



Performance on evaluating Regular Expressions on every byte of input stream

1000s of REs @ 100 Mbps	100s of REs @ 280 Mbps
Gigabytes of Memory	100s of MBs of SRAM

Figure 2

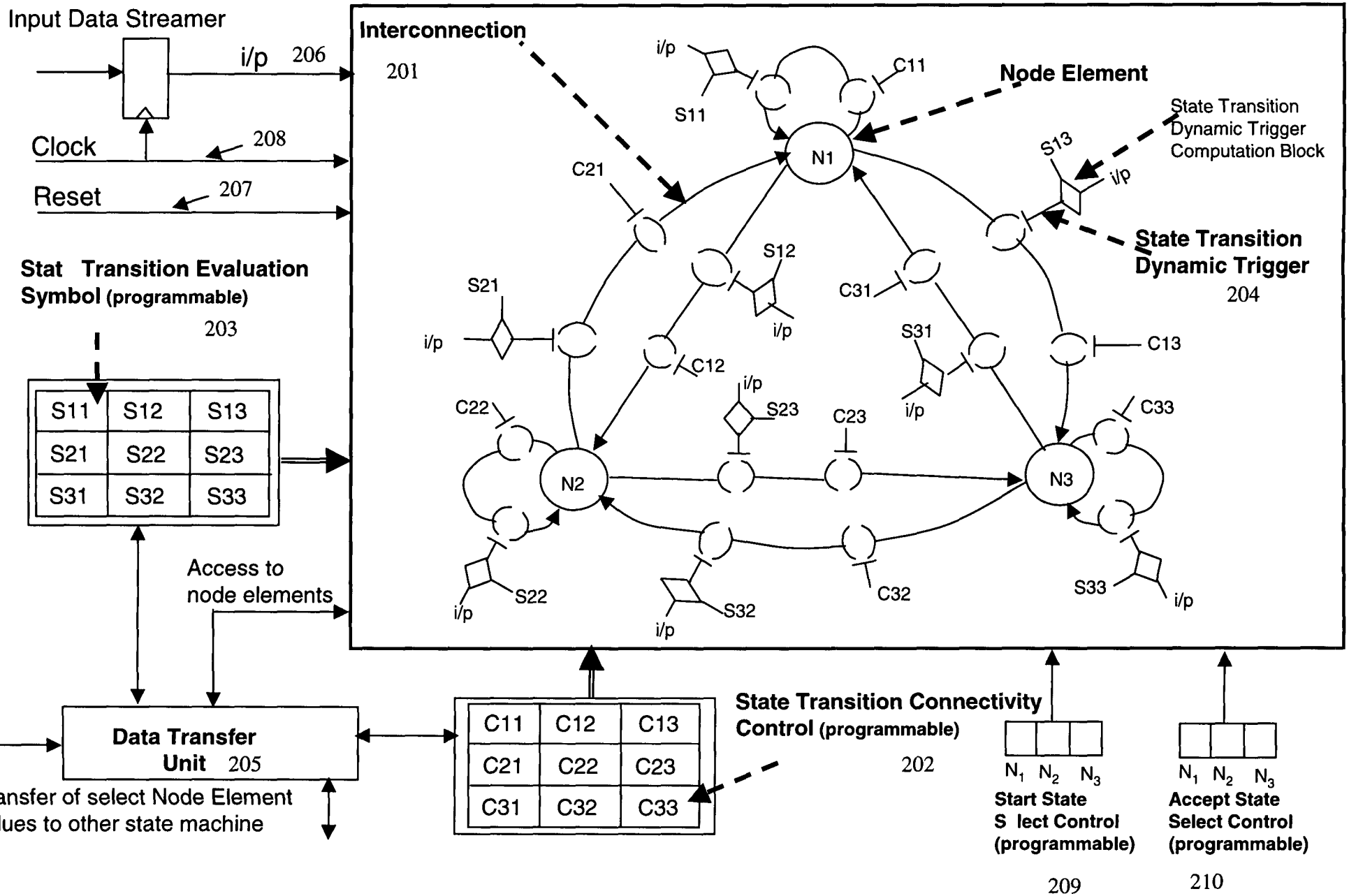

Input Data Streamer
i/p 206
Clock 208
Reset 207
Stat Transition Evaluation Symbol (programmable)
203
S11 S12 S13
S21 S22 S23
S31 S32 S33
Access to node elements
Data Transfer Unit 205
Transfer of select Node Element values to other state machine
Interconnection
201
Node Element
State Transition Dynamic Trigger Computation Block
State Transition Dynamic Trigger
204
N1
N2
N3
C11 C12 C13
C21 C22 C23
C31 C32 C33
State Transition Connectivity Control (programmable)
202
N1 N2 N3
Start State S lect Control (programmable)
209
Accept State Select Control (programmable)
210

Figure 3(a)

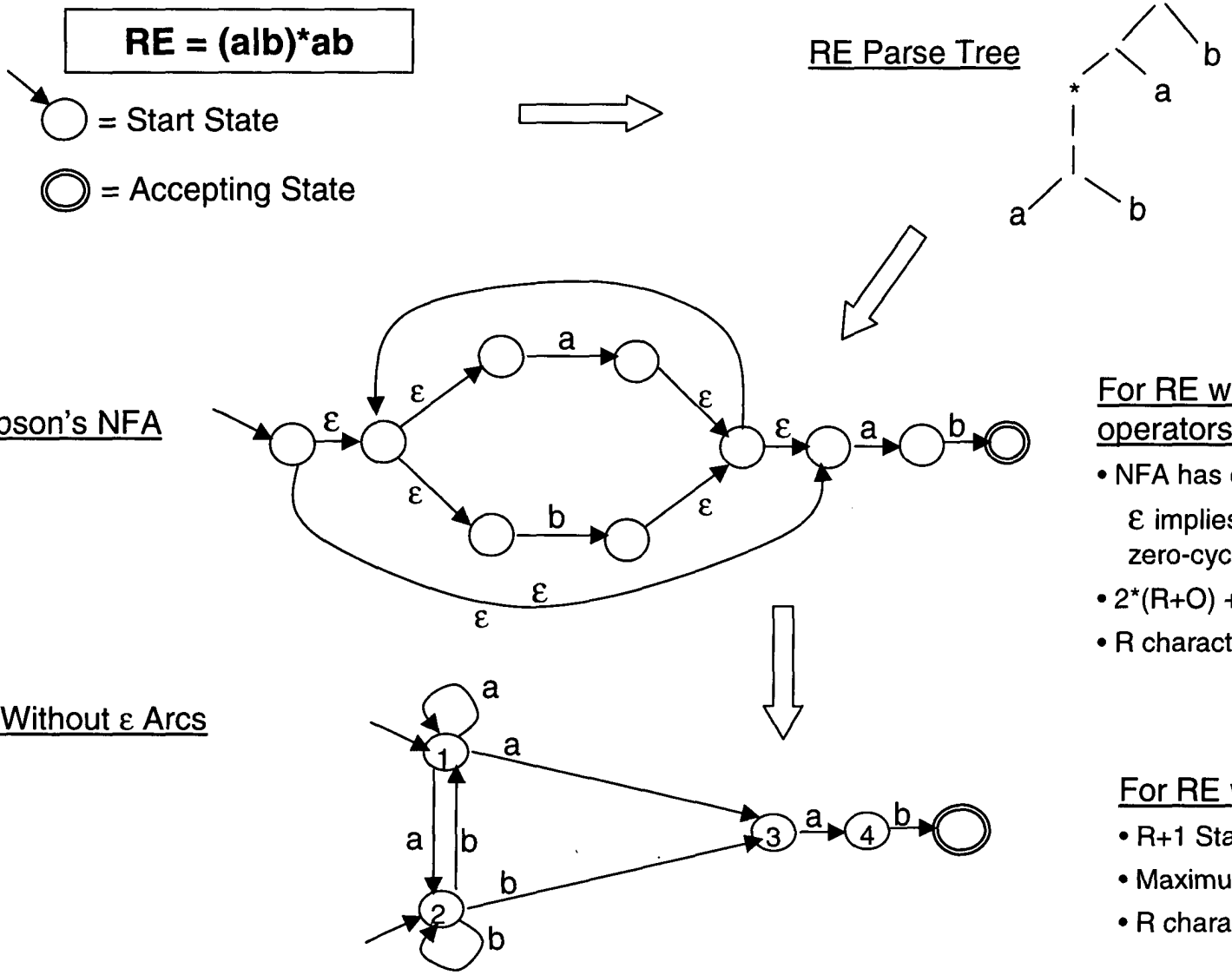

RE = (a|b)*ab
= Start State
= Accepting State
RE Parse Tree
b
*
a
a
b
Thompson's NFA
ε
a
ε
ε
ε
a
b
ε
b
ε
ε
ε
NFA Without ε Arcs
a
a
1
a
b
3
a
4
b
b
2
b
For RE with R chars and O operators
• NFA has epsilon transitions (ε).
ε implies a special unconditional zero-cycle state transition
• 2*(R+O) + 1 states
• R character comparators
For RE with R chars
• R+1 States
• Maximum R^2 Arcs
• R character comparators

Figure 3(b)

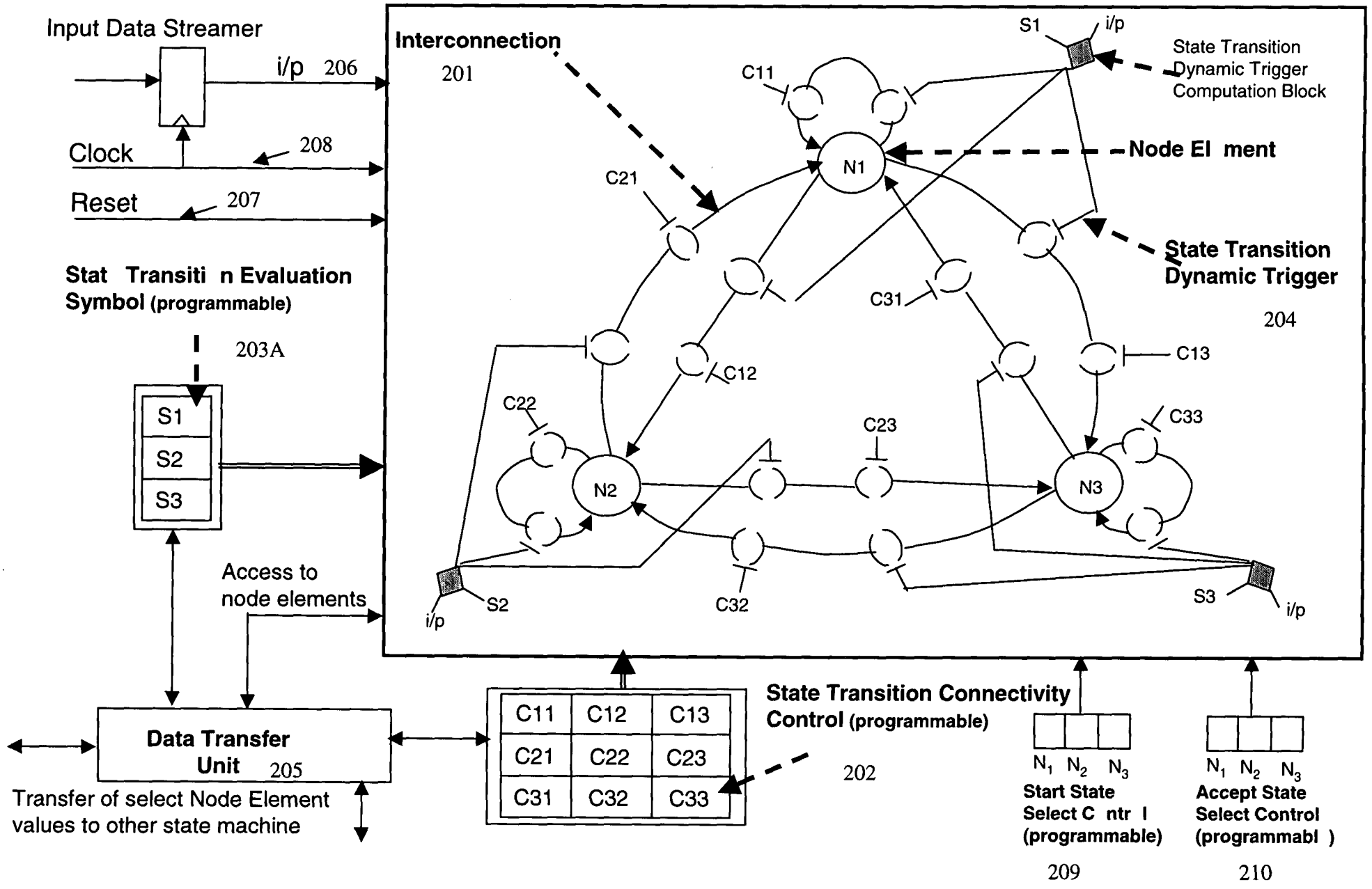

Input Data Streamer
i/p 206
Clock
208
Reset
207
Stat Transiti n Evaluation Symbol (programmable)
203A
S1
S2
S3
Access to node elements
Interconnection
201
S1
i/p
State Transition Dynamic Trigger Computation Block
C11
N1
Node El ment
C21
State Transition Dynamic Trigger
204
C31
C13
C12
C22
C23
C33
N2
N3
i/p
S2
C32
S3
i/p
Data Transfer Unit 205
Transfer of select Node Element values to other state machine
C11 C12 C13
C21 C22 C23
C31 C32 C33
State Transition Connectivity Control (programmable)
202
N1 N2 N3
Start State Select C ntr l (programmable)
209
N1 N2 N3
Accept State Select Control (programmabl)
210

Figure 4

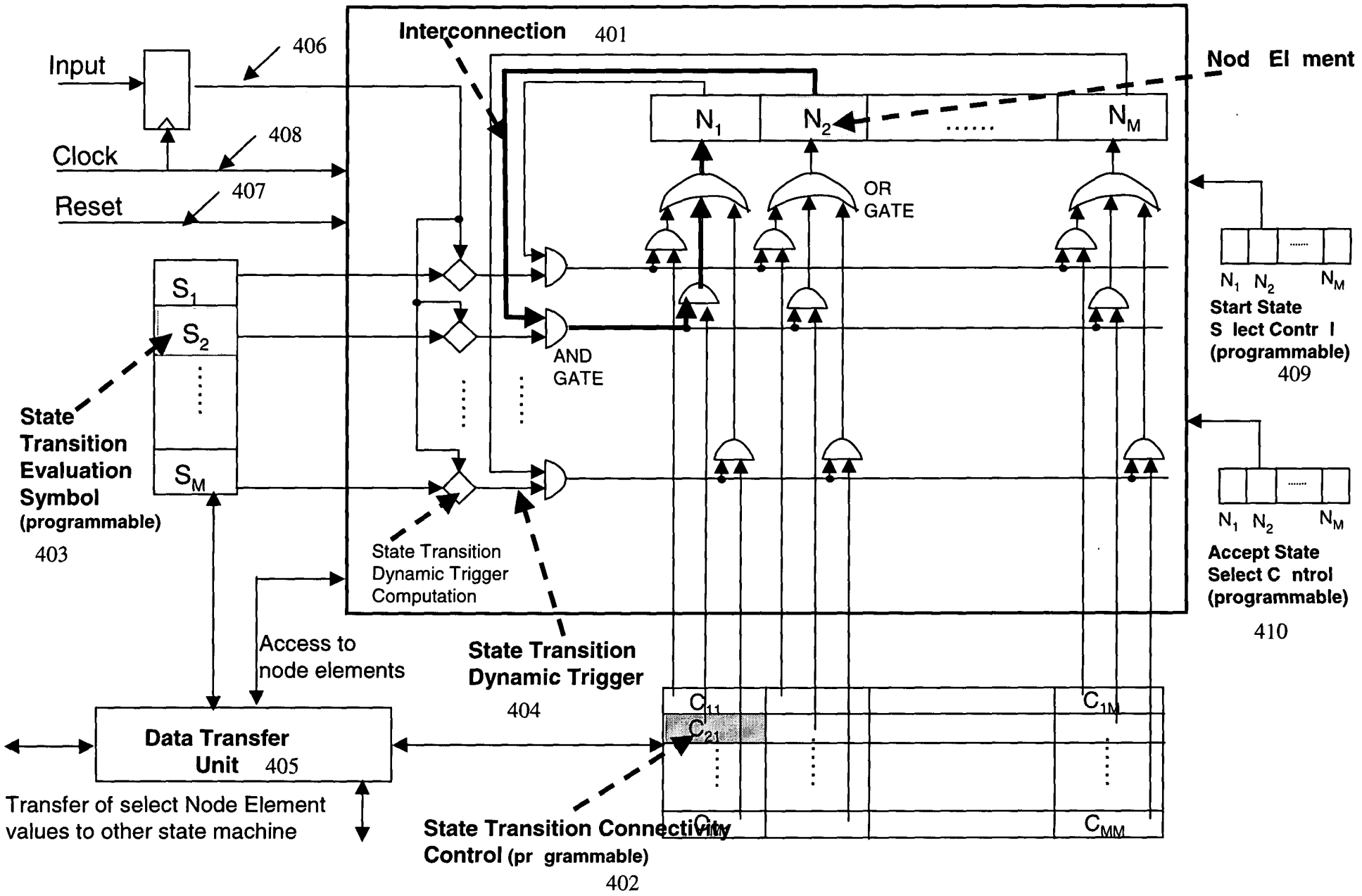

Interconnection 401
Input
406
Clock
408
Reset
407
Nod El ment
N1
N2
.....
NM
OR
GATE
S1
S2
SM
AND
GATE
N1 N2 NM
Start State
S lect Contr l
(programmable)
409
State
Transition
Evaluation
Symbol
(programmable)
403
State Transition
Dynamic Trigger
Computation
N1 N2 NM
Accept State
Select C ntrol
(programmable)
410
Access to
node elements
State Transition
Dynamic Trigger
404
C11
C21
C1M
CMM
Data Transfer
Unit 405
Transfer of select Node Element
values to other state machine
State Transition Connectivity
Control (pr grammable)
402

Figure 5

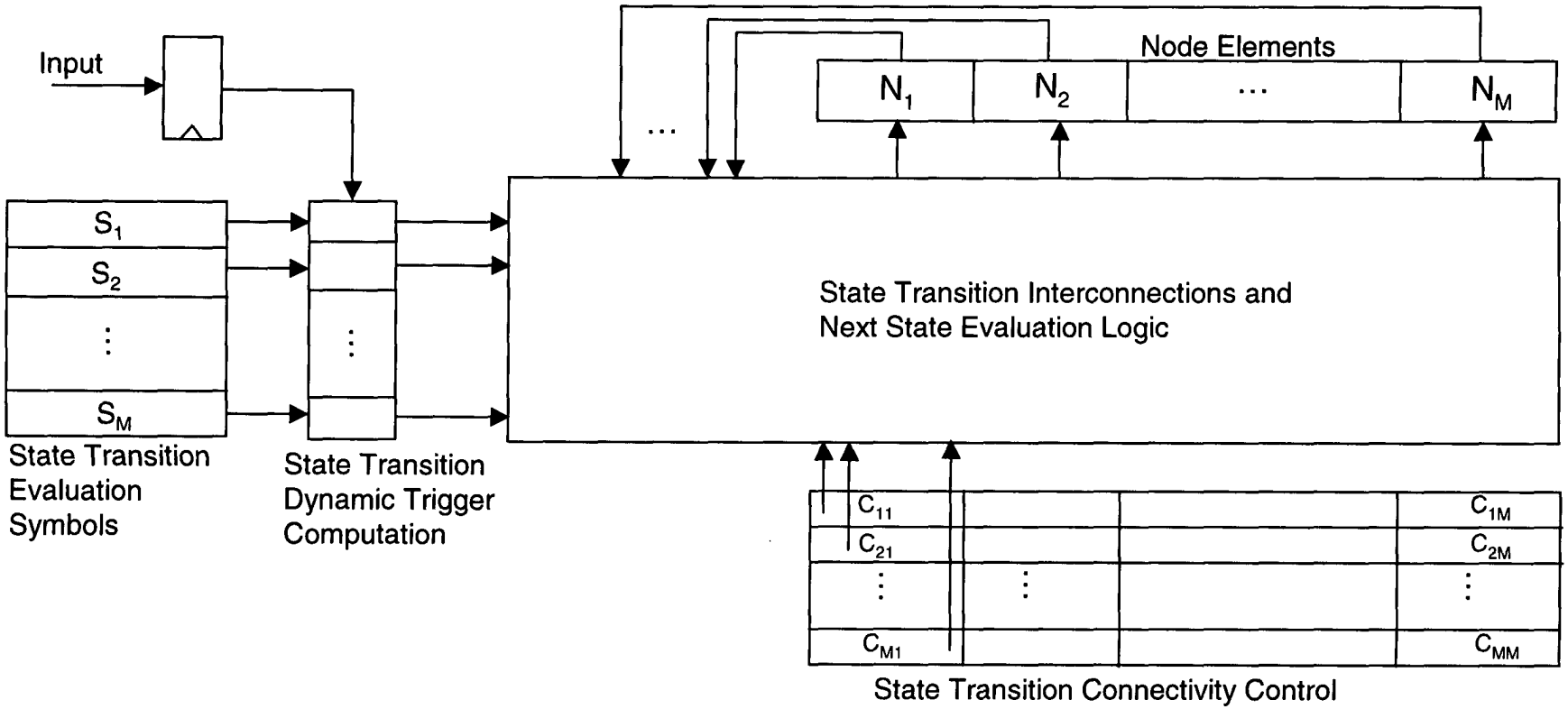

Input
Node Elements
N_1
N_2
...
N_M
S_1
S_2
S_M
State Transition Interconnections and
Next State Evaluation Logic
State Transition
Evaluation
Symbols
State Transition
Dynamic Trigger
Computation
C_{11}
C_{1M}
C_{21}
C_{2M}
C_{M1}
C_{MM}
State Transition Connectivity Control

Figure 6

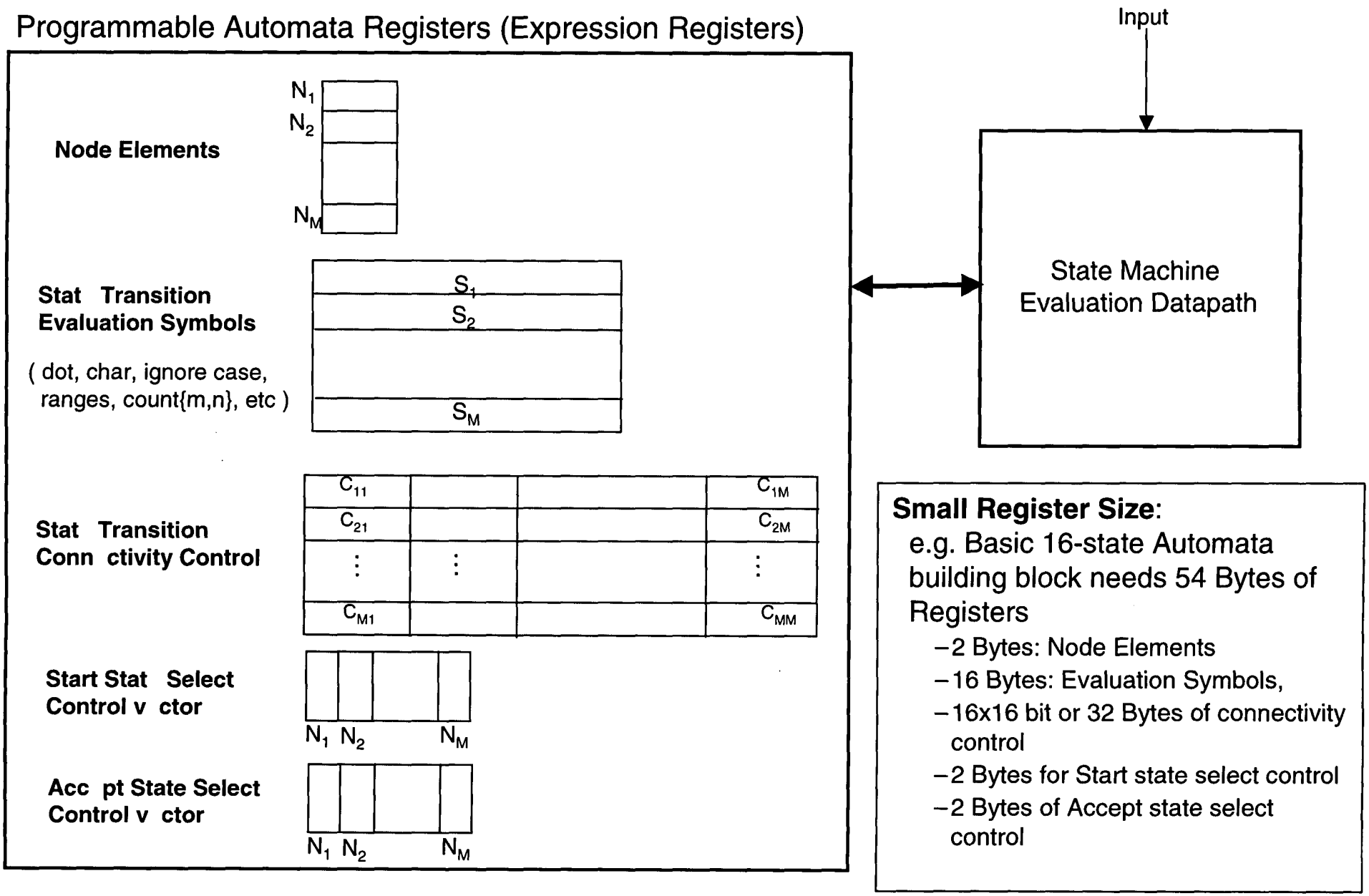
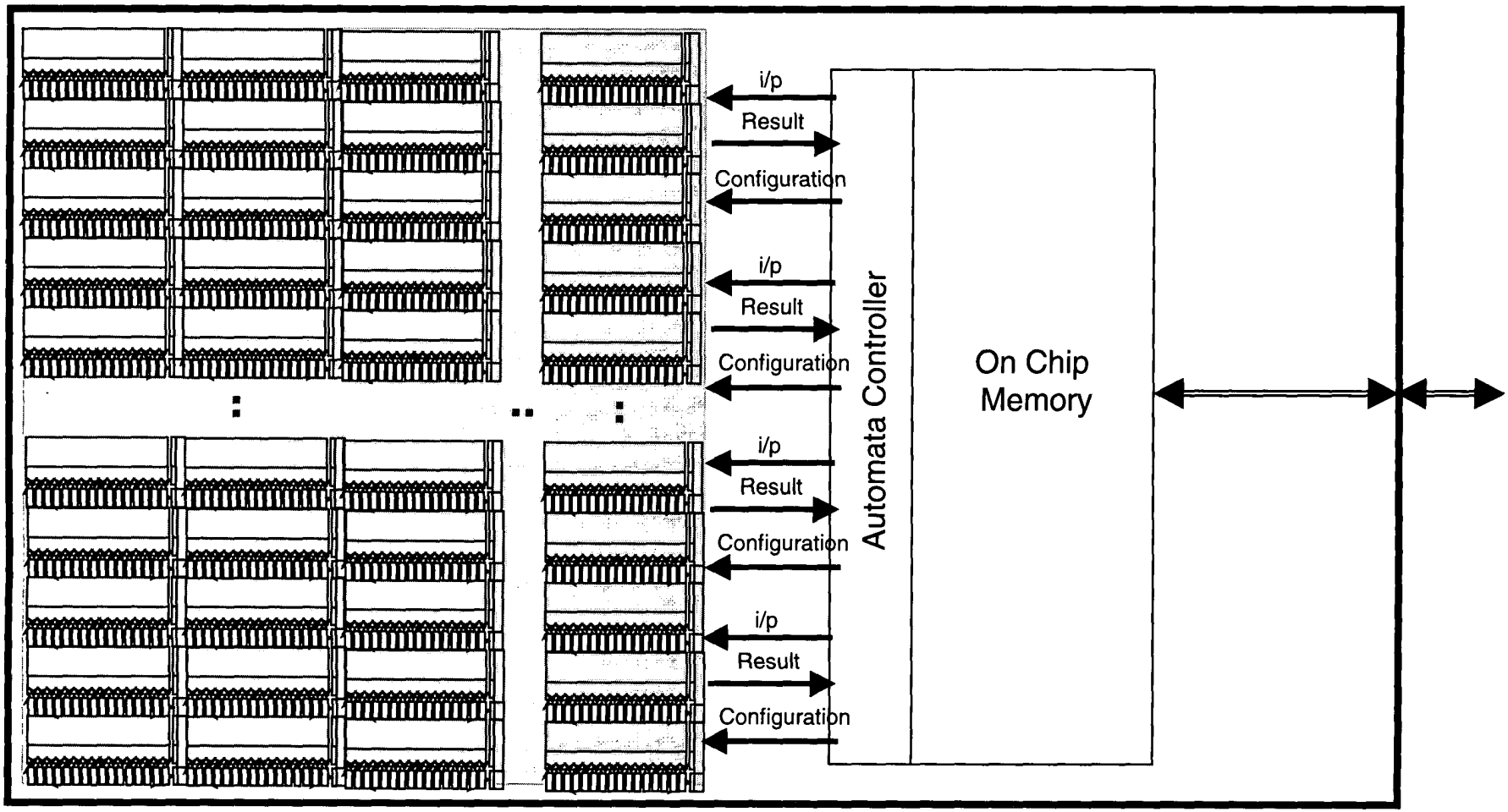

Programmable Automata Registers (Expression Registers)
Input
Node Elements
N1
N2
NM
Stat Transition Evaluation Symbols
(dot, char, ignore case, ranges, count{m,n}, etc)
S1
S2
SM
State Machine Evaluation Datapath
Stat Transition Conn ctivity Control
C11
C1M
C21
C2M
CM1
CMM
Start Stat Select Control v ctor
N1 N2 NM
Acc pt State Select Control v ctor
N1 N2 NM
Small Register Size:
e.g. Basic 16-state Automata building block needs 54 Bytes of Registers
–2 Bytes: Node Elements
–16 Bytes: Evaluation Symbols,
–16x16 bit or 32 Bytes of connectivity control
–2 Bytes for Start state select control
–2 Bytes of Accept state select control

Fig 7

- Simple regular structure enables a high density → dense array of multiple tiles

  Several thousands of automata (organized as multiple rows of tiles) can fit on a singe die on 0.13u technology



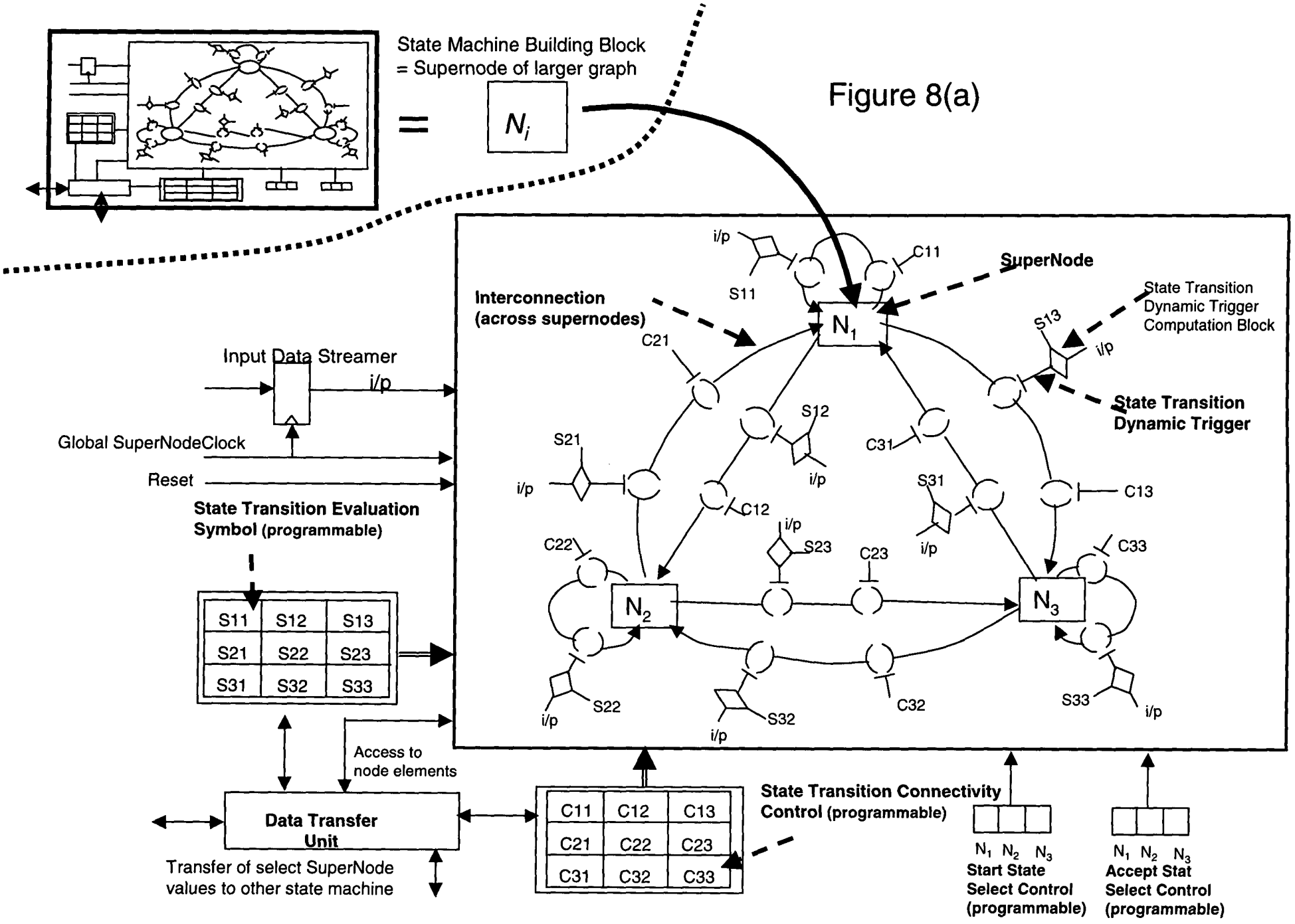
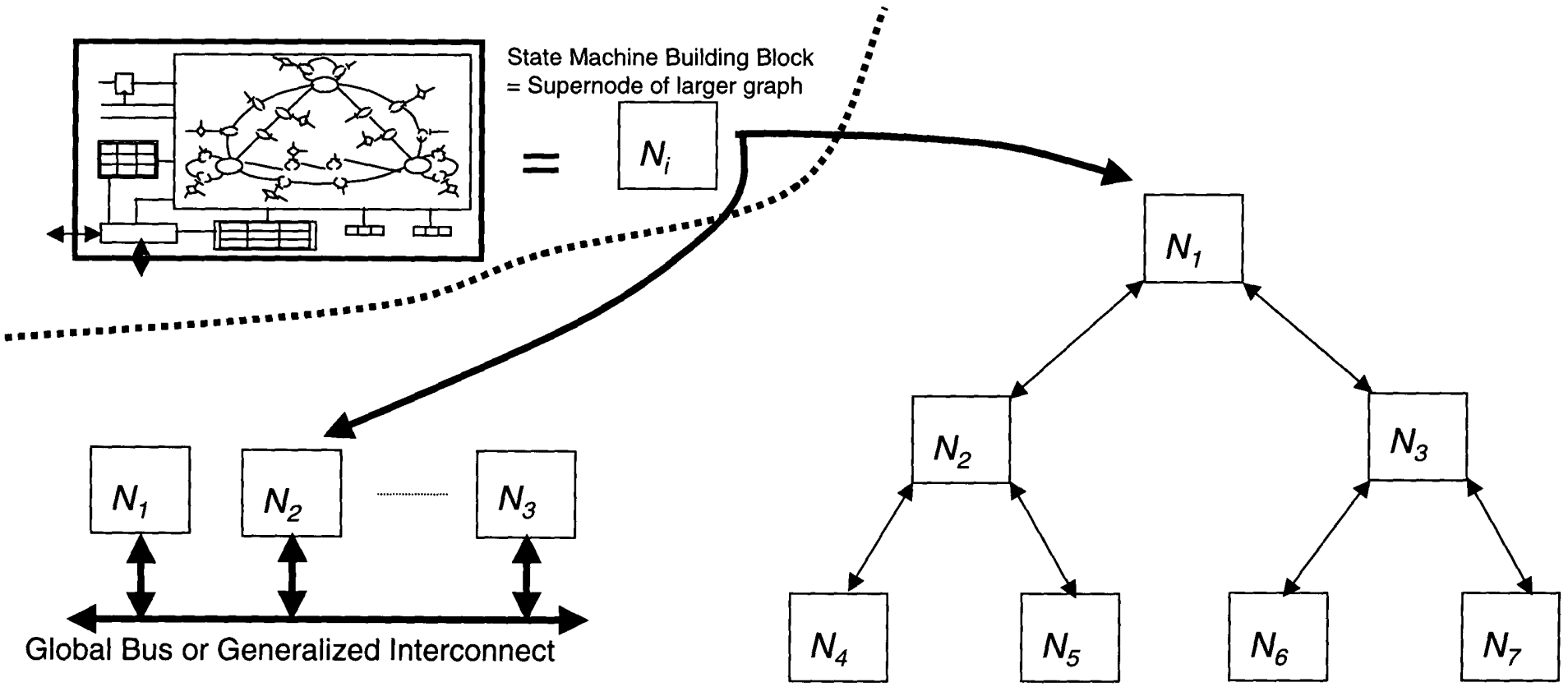

State Machine Building Block
= Supernode of larger graph
N_i
Figure 8(a)
SuperNode
Interconnection
(across supernodes)
State Transition
Dynamic Trigger
Computation Block
State Transition
Dynamic Trigger
Input Data Streamer
i/p
Global SuperNodeClock
Reset
State Transition Evaluation
Symbol (programmable)
S11 S12 S13
S21 S22 S23
S31 S32 S33
Access to
node elements
Data Transfer
Unit
Transfer of select SuperNode
values to other state machine
C11 C12 C13
C21 C22 C23
C31 C32 C33
State Transition Connectivity
Control (programmable)
N_1 N_2 N_3
Start State
Select Control
(programmable)
N_1 N_2 N_3
Accept Stat
Select Control
(programmable)
N_1
N_2
N_3
i/p
C11
S11
C21
S12
S13
S21
C31
C12
S23
S31
C13
C22
C23
C33
S22
S32
C32
S33

Figure 8(b)



Larger Stat Machine Realized via Multiple State Machine Building Blocks on a Gen ral Interconnect

Larger State Machine Realized via Multiple State Machine Building Blocks Organized as a Tree

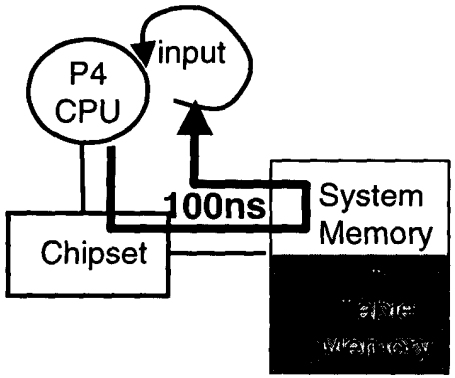
Prior Art

Figure 9(a)

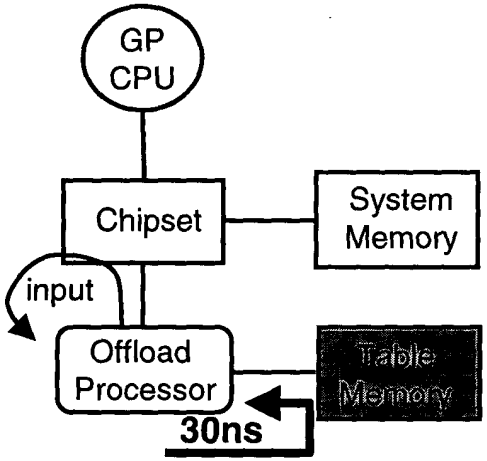
Properties of DFA and NFA techniques used on conventional microprocessors	**Storage: Bound on # of States (for R characters)**	**Evaluation time (for N bytes) [order of]**
D terministic Finite State Automata or DFA running on a GP CPU	**2^R** (needs very large memory)	**N** memory access cycles (~100ns)
Non-Deterministic Finite State Automata or NFA running on a GP CPU	**R**	**R * N** cpu cache+branch cycles (~4ns)
Non-Deterministic Finite State Automata r NFA running on the Apparatus	**R**	**N** Tight on chip state transition cycle (~1 ns)

Figure 9(b)

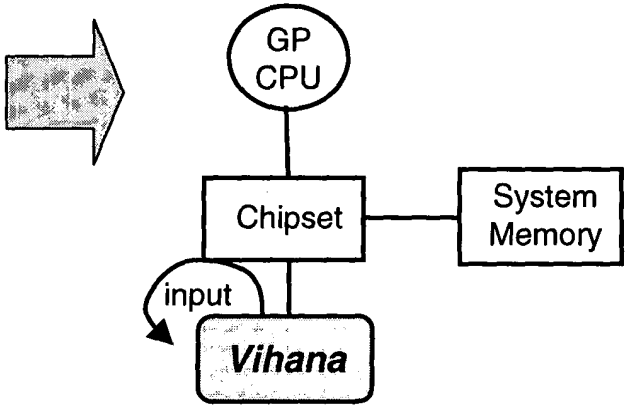
CPU walking DFA table in DRAM



Coprocessor closer to table in SRAM



Regular Expression Co-processor using Exemplary State machine Architecture



Perf on REs on every byte		
1000s of REs @ 100Mbps	100s of REs @ 280Mbps	**1000s of REs @ > 10Gbps**
Gigabytes of Memory	100s of MBs of SRAM	**No table memory needed**

Two orders of magnitude speedup without need for table memory